

# ON THE VALUE OF POPULATION IN DISTRIBUTED CONTROL MODELS

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# Motivation I

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- Research and management regularly assign values to populations as well as to individual members of a population:
  - Demography / evolutionary biology: Reproductive value, evolutionary fitness
  - Resource management: Hotelling rule, Hartwick rule, etc. assign values (e.g. of instantaneous harvest as opposed to future harvest)
  - Environmental management (i): use value + option value + non-use value
  - Environmental management (ii): Environmental impact of humans (e.g. carbon footprint)
  - Business management: capital stock, inventory



# Motivation 2

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## Valuing human life:

“Economists know the price of everything but the value of nothing” (Oscar Wilde)

- Value of a statistical life in medicine, health and environmental economics, occupational safety, public policy
- Human capital
- Valuing birth control (in terms of development impacts)
- Valuing environmental impact of a person (e.g. carbon footprint)



# Motivation 3

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## Conceptually:

- Valuations can be implicit (shadow price of population stock) or...
- ...explicit, e.g. the reproductive value (measured in numbers of offspring) or the statistical value of life (measured in money)

## Our contribution (Wrzaczek et al., Theoretical Population Biology, 2010):

- Formal link between implicit valuations in distributed control models and (economic) valuations
- Applications to health economics, epidemiology, resource management in a predator-prey-setting.



# Basics

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## Population decrement (McKendrick equation):

$$N_a + N_t = -\mu(a, t)N(a, t) \qquad N(0, t) = B(t), N(a, 0) = N_0(a)$$

## Population renewal:

$$B(t) = \int_0^{\omega} \underbrace{\nu(a, t)N(a, t)}_{\text{fertility at age } s} da$$

## (Remaining) Reproductive value (Fisher, 1930):

$$\psi^R(a, t) = \int_a^{\omega} e^{-n(s-a)} \underbrace{\frac{l(s, t-a+s)}{l(a, t)}}_{\text{survival from } a \text{ to } s} \nu(s, t-a+s) ds$$

Rate of population growth



# Application I: Survival investments vs. consumption

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- Planner maximizes social welfare of an aged structured population over time by choosing consumption  $c(a,t)$  and survival investments  $h(a,t)$
- Optimal allocation rule for  $h(a,t)$  embraces the statistical value of life amended by a value of progeny (Kuhn et al. 2010)

## State dynamics:

Population  $\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)N(a,t) = -\mu(a, h(a,t))N(a,t) \quad N(0,t) = B(t), N(a,0) = N_0(a)$

exogenous income

Wealth  $\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)A(a,t) = rA(a,t) + (y(a) - c(a,t) - h(a,t))N(a,t)$

interest rate

$$A(0,t) = A(\omega,t) = 0 \quad \forall t$$

$$A(a,t) = A_0(a), A(a,T) = A_T(a) \quad \forall a,$$



# Application I: Survival investments vs. consumption

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**Social welfare objective:**

$$\max_{c(a,t), h(a,t)} \int_0^T \int_0^\omega e^{-\rho t} \underbrace{u(c(a,t))}_{\text{flow utility}} N(a,t) da dt$$

rate of time preference

s.t. population and wealth dynamics + boundary conditions

**Value of the population state:**

$$\xi^N(a,t) = \int_a^\omega e^{-\rho(s-a)} \frac{l(s,t-a+s)}{l(a,t)} \left[ \underbrace{u(c)}_{\text{Direct „value“}} + u_c(c)(y - c - h) \right] ds$$

$$+ \underbrace{\int_a^\omega e^{-\rho(s-a)} \frac{l(s,t-a+s)}{l(a,t)} \nu(s,t-a+s) \xi^N(0,t-a+s) ds}_{\text{Productive value}}$$

(Remaining) reproductive value

# Application I: Survival investments vs. consumption

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## First-order conditions on controls:

$$\mathcal{H}_c = u_c(c)N - \xi^A N = 0$$

consumption smoothing across age-groups

$$\mathcal{H}_h = -\xi^N \mu_h(a, h)N - \xi^A N = 0$$

optimal survival investments

or in economic terms:

$$\underbrace{-\frac{1}{\mu_h(a, h)}}_{\text{effective \$ cost of saving one life}} = \frac{\xi^N}{\xi^A} = \underbrace{\psi^N(a, t)}_{\text{monetary value of a life saved}}$$

effective \$ cost of saving one life

monetary value of a life saved





# Application I: Survival investments vs. consumption

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## Monetary value of survival

\$ Value of a statistical life (as e.g. in Shepard & Zeckhauser, 1984, MSI)

$$\psi^N(a, t) = \int_a^\omega e^{-r(s-a)} \frac{l(s, t-a+s)}{l(a, t)} \left[ \frac{u(c)}{u_c(c)} + (y - c - h) \right] ds + \int_a^\omega e^{-r(s-a)} \frac{l(s, t-a+s)}{l(a, t)} \nu(s, t-a+s) \frac{u_c(c(0, t-a+s))}{u_c(c(s, t-a+s))} \psi^N(0, t-a+s) ds$$

Consumer surplus  
=\$ value of utility

\$ value of a birth at age s

Conversion from „newborn“ values into survivor’s values (at age s)



# Application I: Survival investments vs. consumption

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## Value of a birth (value of progeny)

$$\psi^N(0, t) = \underbrace{\int_0^\omega e^{-rs} l(s, t+s) \left[ \frac{u(c)}{u_c(c)} \right] ds}_{\$ \text{ value of a full life lived}} + \underbrace{\int_0^\omega e^{-rs} l(s, t+s) \nu(s, t+s) \frac{u_c(c(0, t+s))}{u_c(c(s, t+s))} \psi^N(0, t+s) ds}_{\$ \text{ value of offspring}}$$

**Note:** zero productive value if life-cycle budget is balanced

**For a stable population & steady state economy:**

$$\psi^N(0, t) = \frac{\int_0^\omega e^{-rs} l(s, t+s) \left[ \frac{u(c)}{u_c(c)} \right] ds}{\int_0^\omega [e^{(r-n)s} - 1] e^{-rs} l(s, t+s) \nu(s, t-a+s) ds} \in [0, \infty) \iff r > n$$

Implies and is implied by dynamic efficiency



# Application II: Management of a predator-prey system

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- Two interacting animal populations: predators (=wolves) and prey (=sheep)
- Optimal culling policies  $u(a,t)$  aimed at wolves and  $w(a,t)$  aimed at sheep
- Predator-prey interaction driven by age-specific hunting effectiveness  $f(a)$  and vulnerability  $g(a)$ ...
- ...translating into:

$$P(t) = \int_0^{\omega} g(a)B(a, t)da \quad \text{Pool of „effective prey“}$$
$$Q(t) = \int_0^{\omega} f(a)R(a, t)da \quad \text{Predatory pressure}$$



# Application II: Management of a predator-prey system

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## Population dynamics

- **Wolves:** natural mortality      human culling at effort  $u(a,t)$

$$\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)R(a,t) = \overbrace{-\mu_R(a)R(a,t)}^{\text{natural mortality}} - \overbrace{h_R(a, u(a,t))}^{\text{human culling at effort } u(a,t)}$$

$$R(0,t) = G(t) = \int_0^\omega \underbrace{\nu_R(a)R(a,t)f(a)P(t)}_{\text{Surviving offspring for a mom aged } a \text{ increases in her hunting success } f(a)P(t)} da, R(a,0) = R_0(a)$$

Surviving offspring for a mom aged  $a$  increases in her hunting success  $f(a)P(t)$

- **Sheep:** natural + wolve-induced mortality depending on „predatory risk“  $g(a)Q(t)$       human culling at effort  $w(a,t)$

$$\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)B(a,t) = \overbrace{-\mu_B(a)B(a,t)g(a)Q(t)}^{\text{natural + wolve-induced mortality depending on „predatory risk“ } g(a)Q(t)} - \overbrace{h_B(a, w(a,t))}^{\text{human culling at effort } w(a,t)}$$

$$B(0,t) = H(t) = \int_0^\omega \nu_B(a)B(a,t)da, B(a,0) = B_0(a)$$



# Application II: Management of a predator-prey system

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**Objective: Net present \$ value of the system**

$$\max_{u(a,t), w(a,t)} \int_0^T \int_0^\omega e^{-\rho t} F(R(a,t), B(a,t), u(a,t), w(a,t)) da dt$$

s.t. predator-prey dynamics + boundary conditions

**First-order conditions on controls:**

$$\mathcal{H}_u = F_u - \xi^R(a,t) \frac{\partial h_R(a, u(a,t))}{\partial u(a,t)} = 0$$

$$\mathcal{H}_w = \underbrace{F_w}_{\text{marginal return (through sale of culled animals)}} - \xi^B(a,t) \frac{\partial h_B(a, w(a,t))}{\partial w(a,t)} = 0$$

marginal return (through sale of culled animals)  
– marginal cost of culling



# Application II: Management of a predator-prey system

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## Value of a predator (wolf) aged $a$ at time $t$

$$\xi^R(a, t) = \int_a^\omega e^{-\int_a^s [\rho + \mu_R(s')] ds'} \left( F_R(\cdot) - f(s) \int_0^\omega \mu_B(s') g(s') B(s', t - a + s) \xi^B(s', t - a + s) ds' \right) ds$$

$$+ \underbrace{\int_a^\omega e^{-\int_a^s [\rho + \mu_R(s')] ds'} \xi^R(0, t - a + s) \nu_R(s) f(s) P(t - a + s) ds}_{\text{Value of the predator's offspring: } <0 \text{ for } F_R=0}$$

Direct value of predator (eco-system value?)  $\geq 0$

Value of the predator's offspring:  $<0$  for  $F_R=0$

Loss of prey animals valued at  $\xi^B > 0$  due to increased predatory pressure:  $<0$



# Application II: Management of a predator-prey system

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## Value of a prey animal (sheep) aged $a$ at time $t$

$$\xi^B(a, t) = \int_a^\omega e^{-\int_a^s [\rho + \mu_B(s')g(s')Q(t-a+s')] ds'} \left( F_B(\cdot) + g(s) \int_0^\omega \nu_R(s') f(s') R(s', t-a+s) \xi^R(0, t-a+s) ds' \right) ds + \int_a^\omega e^{-\int_a^s [\rho + \mu_B(s')g(s')Q(t-a+s')] ds'} \xi^B(0, t-a+s) \nu_B(s) ds$$

Direct use value of prey (e.g. value of wool, milk, etc.) + option value of future cull  $>0$

Value of the prey's offspring:  $>0$  for  $F_B > 0$  (suff. large)

Support of predator offspring valued at  $\xi^R < 0$  due to greater pool of prey:  $<0$



# Application III: HIV prevention

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- Two populations: susceptibles (S) and infected (I)
- Susceptible age group  $S(a,t)$  interacts with infected at an age-specific rate

$$P(a, t) = \int_0^{\omega} \lambda(a, a') \frac{I(a', t)}{S(a', t) + I(a', t)} da'$$

- with  $\gamma(a)$  = base risk of infection and  $\phi(u(a,t)) \leq 1$  the impact of an prevention effort  $u(a,t)$  the number of newly infected amongst age group  $a$  at time  $t$  is given by

$$\gamma(a)\phi(u(a, t))P(a, t)S(a, t)$$





# Application III: HIV prevention

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## Population dynamics

- Susceptibles:**

$$\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)S(a, t) = \overbrace{-\mu_S(a)S(a, t)}^{\text{Natural deaths}} - \overbrace{\gamma(a)\phi(u(a, t))P(a, t)S(a, t)}^{\text{New infections}}$$

$$S(0, t) = \underbrace{B(t)}_{\text{Births by susceptibles}} + \underbrace{\alpha C(t)}_{\text{Non-infected births by the infected}}, S(a, 0) = S_0(a)$$

Births by susceptibles      Non-infected births by the infected

- Infected:**

$$\left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)I(a, t) = \overbrace{-\mu_I(a)I(a, t)}^{\text{Deaths from infection (or other)}} + \overbrace{\gamma(a)\phi(u(a, t))P(a, t)S(a, t)}^{\text{New infections}}$$

$$I(0, t) = \underbrace{(1 - \alpha)C(t)}_{\text{Infected births by the infected}}, I(a, 0) = I_0(a)$$

- with**  $B(t) = \int_0^\omega \nu_S(a, t)S(a, t)da$       Infected births by the infected

$$C(t) = \int_0^\omega \nu_I(a, t)I(a, t)da$$



# Application III: HIV prevention

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**Objective: Minimise the total cost of infection plus prevention**

$$\max_{u(a,t)} - \int_0^T \int_0^\omega e^{-\rho t} \left( \underbrace{F(I(a,t))}_{\text{Cost of infection related to age group } a \text{ at time } t} + \underbrace{u(a,t)}_{\text{Prevention cost related to age group } a \text{ at time } t} \right) da dt$$

Cost of infection related to age group  $a$  at time  $t$

Prevention cost related to age group  $a$  at time  $t$

**First-order condition on control:**

$$\mathcal{H}_u = \underbrace{-1}_{\text{Marginal \$ spent on prevention}} - \underbrace{\gamma(a) P(t) S(a,t)}_{\text{Marginal number of infections prevented}} \frac{\partial \phi}{\partial u} \underbrace{\left[ \xi^S(a,t) - \xi^I(a,t) \right]}_{\text{Value of averting an infection}} = 0$$

Marginal \$ spent on prevention

Marginal number of infections prevented

Value of averting an infection

# Application III: HIV prevention

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## Value of a susceptible (in terms of HIV-related costs)

Expected value of becoming infected (<0)

Value in lowering disease prevalence and infection risk: typically >0

$$\xi^S(a, t) = \int_a^\omega e^{-\int_a^s [\rho + \mu_S(s') + \gamma\phi(u)P] ds'} \left[ \gamma\phi(u)P\xi^I - \int_0^\omega \zeta(t, a') \frac{\lambda I}{(S + I)^2} da' \right] ds + \int_a^\omega e^{-\int_a^s [\rho + \mu_S(s') + \gamma\phi(u)P] ds'} \xi^S(0, t - a + s) \nu_S(s) ds$$

Value of non-infected children



# Application III: HIV prevention

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## Value of an infected (in terms of HIV-related costs)

Contribution of an additional infected to the cost of infection

Value of raising disease prevalence and infection risk: typically  $<0$

$$\xi^I(a, t) = \int_a^\omega e^{-\int_a^s [\rho + \mu_I(s')] ds'} \left[ -F_I(I) + \int_0^\omega \zeta(t, a') \frac{\lambda S}{(S + I)^2} da' \right] ds$$

$$+ \int_a^\omega e^{-\int_a^s [\rho + \mu_I(s')] ds'} \left( \underbrace{\alpha \xi^S(0, t - a + s)}_{\text{Expected value of non-infected children}} + \underbrace{(1 - \alpha) \xi^I(0, t - a + s)}_{\text{Expected value of infected children } <0 \text{ if } \alpha \rightarrow 0} \right) \nu_I(s) ds$$

Expected value of non-infected children

Expected value of infected children  $<0$  if  $\alpha \rightarrow 0$



# Conclusion

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- Shadow prices on population states can be interpreted as values of population. These could be directly in \$ terms if the objective function is in \$, or they could be converted into \$ terms, als in case of the value of human survival.
- As such they can be used to
  - (a) compare the valuations in the model against the data (to check e.g. if components of the model are missing)
  - (b) to calibrate the model to the data
  - (c) to provide policy guidance.
- An analysis of the components of the shadow price allows to identify components relevant to the valuation (and the mechanisms behind the model)
- In age-structured models of long-term development of the population, the value of population falls into a „direct“ part relating to the contemporary individual/cohort, and an indirect relating to the value of the individuals expected offspring
- The value of population is age-specific in a non-trivial way



# Appendix: General model

Salvage value related to non-pop states

$$\max_{u,v,w} \int_0^T \int_0^\omega e^{-\rho t} L(a, t, N, Y, Q, P, u, v, w) da dt + \int_0^\omega e^{-\rho T} l(a, Y(a, T)) da$$

$$\text{s.t.} \quad \left( \frac{\partial}{\partial a} + \frac{\partial}{\partial t} \right) N(a, t) = -\mu(a, t, N, Y, Q, P, u)N + g(a, t, N, Y, Q, P, u) \leftarrow \text{Other population change}$$

$$N(0, t) = B(t) = \int_0^\omega \nu(a, t, N, Y, Q, P, u) N da, N(a, 0) = N_0(a)$$

Density dependent mortality and fertility

$$\left( \frac{\partial}{\partial a} + \frac{\partial}{\partial t} \right) Y(a, t) = f(a, t, N, Y, Q, P, u)$$

Non-population states

$$Y(0, t) = \varphi(t, B, Q, v), Y(a, 0) = Y_0(a, w)$$

$$Q(t) = \int_0^\omega h(a, t, N, Y, Q, P, u) da$$

Boundary states

$$P(a, t) = \int_0^\omega k(a, t, a', N, Y, u) da'$$

Interaction states

$$u(a, t) \in U, v(t) \in V, w(a) \in W$$

Age-structured controls

Boundary controls

Initial controls



# Appendix: General model

The distributed, initial and boundary Hamiltonian of the general model reads as follows

$$\begin{aligned}
 \mathcal{H}(\cdot) &= L + \xi^N(-\mu N + g) + \xi^Y f + \eta^B \nu N + \eta^Q h + \int_0^\omega \zeta k(a, t, a', u) da' \\
 \mathcal{H}_0(\cdot) &= \xi^N(a, 0)N_0(a) + \xi^Y(a, 0)Y_0(a, w) + \int_0^T L(a, t, w) dt \\
 \mathcal{H}_b(\cdot) &= \xi^N(0, t)B(t) + \xi^Y(0, t)\varphi(t, v) + \int_0^\omega L(a, t, v) da. \tag{1}
 \end{aligned}$$

Applying distributed optimal control theory (see Feichtinger et al. (2003)) we obtain the following adjoint system

$$\begin{aligned}
 \xi_a^N + \xi_t^N &= (\rho + \mu + \mu_N N)\xi^N - L_N - \xi^N g_N - \xi^Y f_N - \eta^B(\nu_N N + \nu) - \eta^Q h_N - \int_0^\omega \zeta^P k_N da' \\
 \xi_a^Y + \xi_t^Y &= (\rho + f_Y)\xi^Y - L_Y + \xi^N \mu_Y N - \xi^N g_Y - \eta^B \nu_Y N - \eta^Q h_Y - \int_0^\omega \zeta^P k_Y da' \\
 \eta^B &= \xi^N(0, t) + \xi^Y(0, t)\varphi_B \\
 \eta^Q &= \xi^Y(0, t)\varphi_Q + \int_0^\omega L_Q + \xi^N(-\mu_Q N + g_Q) + \xi^Y f_Q + \eta^B \nu_Q N + \eta^Q h_Q da \\
 \zeta^P &= L_P + \xi^N(-\mu_P N + g_P) + \xi^Y f_P + \eta^B \nu_P N + \eta^Q h_P
 \end{aligned}$$



# Appendix: General model

together with the transversality conditions

$$\begin{aligned}\xi^N(a, T) &= 0 & \xi^N(\omega, t) &= 0 \\ \xi^Y(a, T) &= l_Y(a, T) & \xi^Y(\omega, t) &= 0\end{aligned}$$

Finally the necessary first order conditions can be derived from

$$\begin{aligned}\mathcal{H}(a, t, u^*(a, t)) &\geq \mathcal{H}(a, t, u(a, t)) & \forall u(a, t) \in U \\ \frac{\partial \mathcal{H}_0}{\partial w}(a_0, w^*(a_0))(w - w^*(a_0)) &\leq 0 & \forall w \in W \\ \frac{\partial \mathcal{H}_0}{\partial v}(t_0, v^*(t_0))(v - v^*(t_0)) &\leq 0 & \forall v \in V\end{aligned}$$

where  $u^*(a, t)$  denotes the distributed,  $w^*(a_0)$  the initial and the  $v^*(t_0)$  the boundary optimal control.





# Appendix: General model

$$\begin{aligned} \left(\frac{\partial}{\partial a} + \frac{\partial}{\partial t}\right)\xi^N(a, t) &= (\rho + \mu + \mu_N N - g_N)\xi^N - L_N - \xi^Y f_N - \\ &\quad - \xi^N(0, t - a + s)(\nu_N N + \nu) - \eta^Q h_N - \int_0^\omega \zeta P_N d(\hat{t}) \end{aligned}$$

where  $\xi^Y(a, t)$ ,  $\eta^Q(t)$  and  $\zeta(a, t)$  are the adjoint variables of  $Y$ ,  $Q$  and  $P$  respectively. All adjoint variables can be interpreted as dynamic shadow prices, i.e. they indicate the increase of the objective function if the corresponding state is increased marginally. E.g.  $\xi^N(a, t)$  denotes the increase of the objective function if the population is increased marginally at age  $a$  at time  $t$  (or by one  $a$ -aged individual at  $t$  if the population is large enough). The term shadow price has already been used in the examples.

Together with the transversality condition  $\xi^N(\omega, t) = 0$  the shadow price of the population can be solved with the method of characteristics for all cohorts whose maximal life horizon ends before the planning horizon  $T$

$$\begin{aligned} \xi^N(a, t) &= \int_a^\omega e^{-\int_a^s (\rho + \mu + \mu_N N - g_N) ds'} \left( L_N + \xi^Y f_N + \eta^Q h_N + \int_0^\omega \zeta P_N da' \right) ds + \\ &\quad + \int_a^\omega e^{-\int_a^s (\rho + \mu + \mu_N N - g_N) ds'} \xi^N(0, t - a + s)(\nu + \nu_N N) ds. \end{aligned} \quad (3)$$



# Acknowledgment

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# THANK YOU!